# Compact Linear Actuators **DRS2 Series** *Aster* Az Equipped

## CE

 For detailed information about regulations and standards, please see the Oriental Motor website.



Type with a Guide Built-in Controller Type without a Guide Pulse Input The **DRS2** Series actuators use the  $\mathcal{Q}_{STEP}$  **AZ** Series equipped with Absolute Sensors. The Absolute Sensor is a mechanical and multi-turn, so an external sensor is not required. The **DRS2** Series helps to save space and reduce wiring, as well as offer a more compact and lightweight design.

- Optimized for Providing Micromovements and High Positioning Accuracy
- Reduces Startup Time
- Saves Space and Reduces Wiring with the Absolute Sensor
- Highly Efficient Push-Motion Operation

See Full Product Details Online	● Manual	Specifications	Dimensions
www.orientalmotor.com	• CAD	Characteristics	Connection and Operation

## Features

## Perfect for Micromovements and High Positioning Accuracy

## The Product Integrates a Stepper Motor with a Ball Screw

The hollow rotor and ball screw nut have been integrated. Since no connecting parts are necessary, there is less backlash, higher rigidity, and higher positioning accuracy.

#### Driven by Ground Ball Screw or Rolled Ball Screw

[Min. Traveling Amount] 0.001 mm

[Repetitive Positioning Accuracy]

Ground ball screw:  $\pm 0.003$  mm Rolled ball screw:  $\pm 0.01$  mm

#### High Transportable Mass and High Speed are Achieved

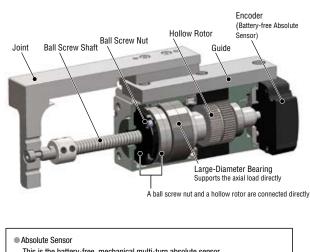
Type with a Guide

[Maximum Transportable Mass]

Horizontal direction: 10 kg (Lead 2 mm), 5 kg (Lead 8 mm)
Vertical direction: 10 kg (Lead 2 mm), 5 kg (Lead 8 mm)

[Maximum Speed]

50 mm/sec (Lead 2 mm), 200 mm/sec (Lead 8 mm)



This is the battery-free, mechanical multi-turn absolute sensor. The inclusion of this compact and low cost absolute system saves space and wiring, because a home sensor is not required.

## Startup Time Reduced

#### Compact Body Houses Entire Linear Motion Mechanism

- Since customers do not need to provide parts, the time needed for installing, designing, and selecting parts can be reduced.
- The number of man-hours required for assembly and adjusting the installation accuracy can be reduced, contributing to higher productivity.

#### Parameters Set at Operation

[Min. Traveling Amount] Built-in Controller Type: 0.001 mm Pulse Input Type : 0.001 mm

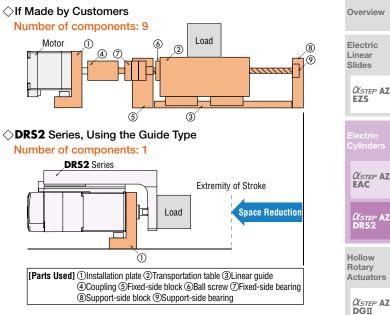
#### Setting in Millimeters

The traveling amount can be set on the millimeter unit.

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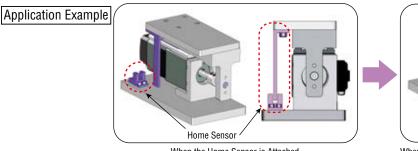
#### Comparison of the Number of Components

Configuration examples of cases where the load is driven by the same stroke



## Space Saving and Less Wiring with the Absolute Sensor

In addition to the compact and lightweight body, the motors with absolute sensors do not require a home sensor. This saves space and wiring, and lets you avoid routine maintenance or trouble caused by using a home sensor.

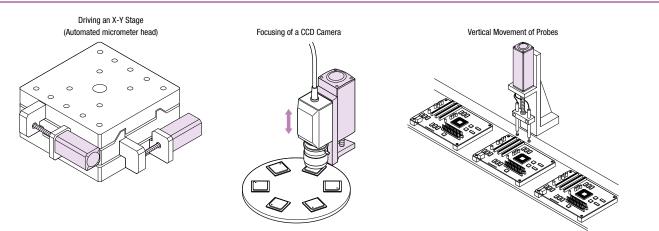


When the Home Sensor is Attached



When the Home Sensor is Not Attached

## **Typical Applications**



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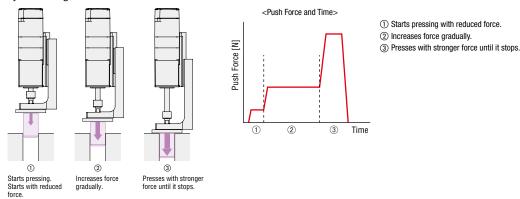
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## **Efficient Push-Motion Operation**

#### Flexible Push Force and Timing

The **DRS2** Series can easily perform a push-motion operation after a positioning operation. Also, the push force and timing are adjustable.

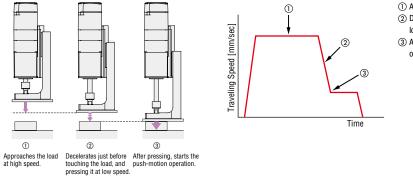
- You can set the push force and push timing to an operation data No., and then select the data No. to operate.
- There are different ways to change the pressing phases, such as dropping the force so that the position does not shift, slowly increasing the force, or rapidly increasing the force.



#### Pressing at Low Speed

The motor can approach the load at high speed. The motor can also decelerate just before hitting the load at low speed.

- Since the pressing impact is minimal, a mechanism for shock absorption is not required.
- The motor can approach at high speed just before reaching the load, thus reducing the takt time.



Approaches the load at high speed.
 Decelerates just before touching the

- load, and pressing it at low speed.
- ③ After pressing, starts the push-motion operation.

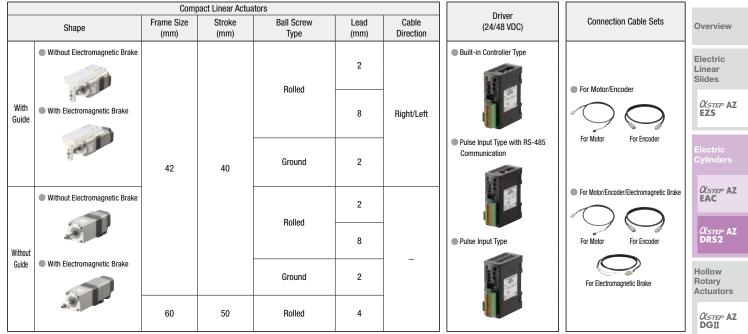
#### Push-Motion Operation with Pulse Input Type

When T-MODE input is set to ON, push-motion operation is possible, without the overload alarm being generated. This is useful for push-motion operation while using pulse signal control.

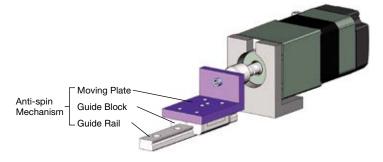
## Linear & Rotary Actuators F-35

## Product Line

For the **DRS2** Series, compact linear actuators, drivers, and a connection cable sets need to be ordered separately. They can be purchased in various combinations.



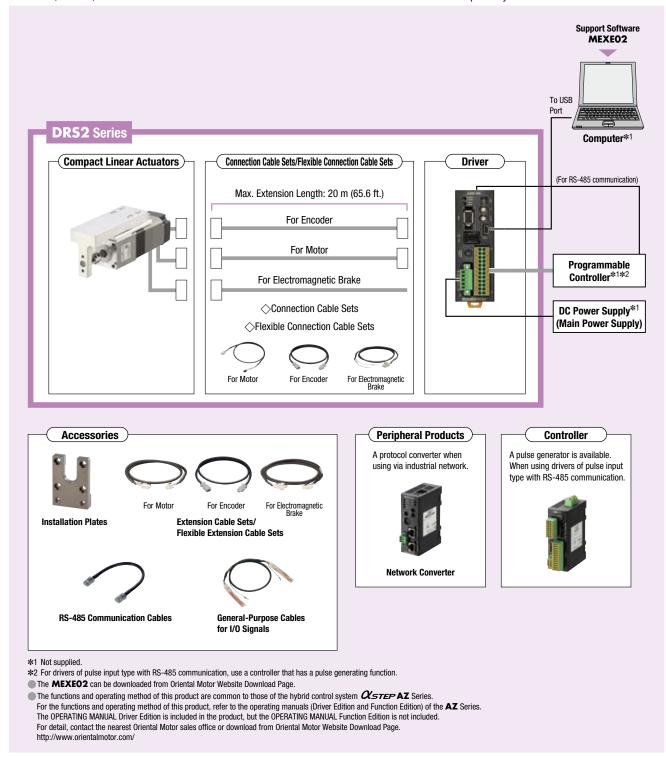
• When the guide is not equipped, anti-spin mechanism is necessary for the screw mechanism.



### System Configuration

Combination of Linear & Rotary Actuator with Electromagnetic Brake, and either Built-in Controller Type Driver or Pulse Input Type Driver with RS-485 Communication.

This is an example of a configuration using I/O control or RS-485 communication in a built-in controller type driver. Actuators, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.



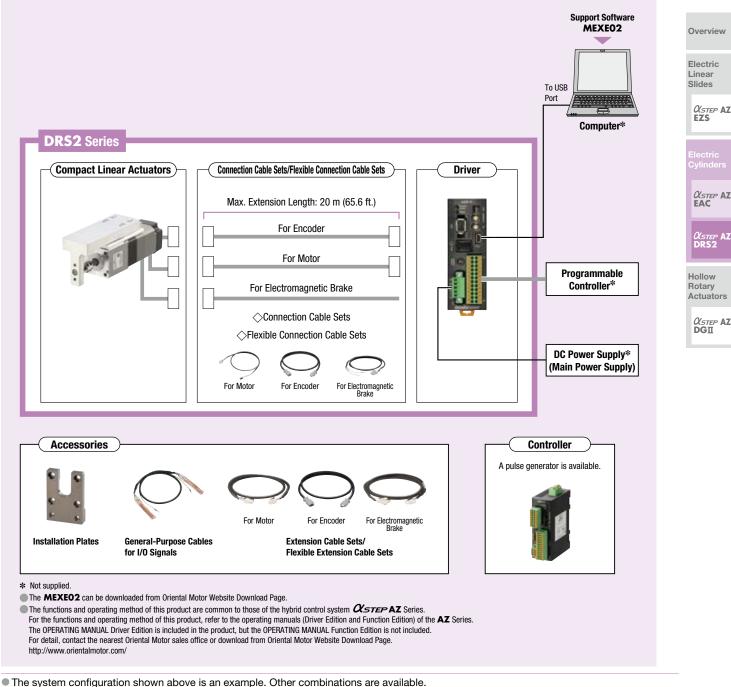
The system configuration shown above is an example. Other combinations are available.

 Note

The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

#### Combination of Linear & Rotary Actuator with Electromagnetic Brake and Pulse Input Type Driver

This is an example of a single-axis system configuration using a programmable controller (with pulse oscillation function). Actuators, drivers, and connection cable sets/flexible connection cable sets need to be ordered separately.



#### Note

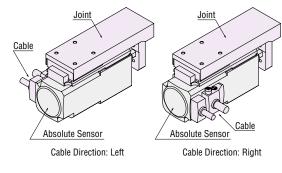
• The motor cable and electromagnetic brake cable from the motor cannot be connected directly to the driver. When connecting to a driver, use a connection cable.

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### Product Number

 $\begin{array}{c} \text{Compact Linear Actuators} \\ \hline \textbf{DRSM} \\ \hline 1 \\ \hline \end{array} \\ \begin{array}{c} \textbf{42} \\ \hline 2 \\ \hline \end{array} \\ \begin{array}{c} \textbf{R} \\ \hline 3 \\ \hline \end{array} \\ \begin{array}{c} \textbf{G} \\ \hline \end{array} \\ \begin{array}{c} \textbf{-} \\ \textbf{04} \\ \hline \end{array} \\ \begin{array}{c} \textbf{A} \\ \hline \textbf{S} \\ \hline \end{array} \\ \begin{array}{c} \textbf{A} \\ \textbf{2} \\ \hline \end{array} \\ \begin{array}{c} \textbf{AZ} \\ \textbf{AZ} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{K} \\ \hline \end{array} \\ \begin{array}{c} \textbf{0} \\ \textbf{0} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \hline \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \textbf{M} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \end{array} \\ \end{array} \\ \end{array} \end{array} \\ \begin{array}{c} \textbf{M} \\ \end{array} \\ \end{array} \\ \end{array} \end{array} \\ \end{array} \\ \end{array} \end{array} \\ \end{array} \\ \end{array}$  \\ \begin{array}{c} \textbf{M} \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \begin{array}{c} \textbf{M} \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \end{array} \\ \end{array} \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \end{array} \\ \end{array} \end{array} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \\ \end{array} \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \\ \\ \end{array} \\ \end{array} \\ \end{array} \\ \end{array} \\ \\ \\ \end{array} \\ \\ \end{array} \\ \\ \end{array} \\ \\ \end{array} \\ \\ \\ \end{array} \\ \\ \\ \end{array} \\ \\ \end{array}

\*The cable outlet direction is only available for the type with a guide. The cable direction is as viewed from the Absolute Sensor with the joint part facing up.





1	Series Name	DRSM: DRS2 Series
2	Frame Size	<b>42</b> : 42 mm <b>60</b> : 60 mm
3	Cable Direction*	R: Right L: Left Blank: Type without Guide
4	Configuration	<b>G</b> : Type with Guide Blank: Type without Guide
5	Stroke	<b>O4</b> : 40 mm <b>O5</b> : 50 mm
6	Ball Screw Type	A: Rolled Ball Screw B: Ground Ball Screw
0	Lead	2: 2 mm 4: 4 mm 8: 8 mm
8	Motor Type	AZ: AZ Series
9	Electromagnetic Brake	A: Without Electromagnetic Brake M: With Electromagnetic Brake

K: DC Input Specification

1	Driver Type	AZD: AZ Series Driver
2	Power Supply Input	<b>K</b> : 24/48 VDC
3	Туре	D: Built-in Controller Type X: Pulse Input Type with RS-485 Communication Blank: Pulse Input Type

Connection Cable Sets/Flexible Connection Cable Sets



1		CC: Cables
2	Length	010:1m 020:2m 030:3m 050:5m 070:7m 100:10m 150:15m 200:20m
3	Reference Number	
4	Applicable Models	Z: AZ Series
5	Cable Type	F: Connection Cable Sets R: Flexible Connection Cable Sets
6	Electromagnetic Brake	Blank: Without Electromagnetic Brake B: With Electromagnetic Brake
0	Cable Specifications	2: DC Power Supply Input

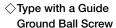
## Product Line

Compact Linear Actuators



With electromagnetic brake

Electromagnetic Brake	Lead [mm]	Cable Direction	Product Name	List Price
	2	Right	DRSM42RG-04A2AZAK	\$920.00
Without Electromagnetic		Left	DRSM42LG-04A2AZAK	\$920.00
Brake	8	Right	DRSM42RG-04A8AZAK	\$1,024.00
		Left	DRSM42LG-04A8AZAK	\$1,024.00
	2	Right	DRSM42RG-04A2AZMK	\$1,127.00
With Electromagnetic Brake		Left	DRSM42LG-04A2AZMK	\$1,127.00
	8	Right	DRSM42RG-04A8AZMK	\$1,231.00
	0	Left	DRSM42LG-04A8AZMK	\$1,231.00



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Motor Specification



With electromagnetic brake

Electromagnetic Brake	Lead [mm]	Cable Direction	Product Name	List Price
Without Electromagnetic		Right	DRSM42RG-04B2AZAK	\$1,233.00
Brake	2	Left	DRSM42LG-04B2AZAK	\$1,233.00
With Electromagnetic	2	Right	DRSM42RG-04B2AZMK	\$1,440.00
Brake		Left	DRSM42LG-04B2AZMK	\$1,440.00

#### **Linear & Rotary Actuators** F-39

#### $\bigcirc$ Type without a Guide **Rolled Ball Screw**



Electromagnetic Brake	Lead [mm]	Product Name	List Price
Without Electromagnetic Brake	2	DRSM42-04A2AZAK	\$667.00
	8	DRSM42-04A8AZAK	\$771.00
	4	DRSM60-05A4AZAK	\$863.00
With Electromagnetic Brake	2	DRSM42-04A2AZMK	\$874.00
	8	DRSM42-04A8AZMK	\$978.00
	4	DRSM60-05A4AZMK	\$1,070.00

## $\bigcirc$ Type without a Guide

Ground Ball Screw

◇For Motor/Encoder/

**Electromagnetic Brake** 



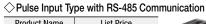
		With	electromagnetic brake	
Electromagnetic Brake	Lead [mm]	Product Name	List Price	Overview
Without Electromagnetic Brake	2	DRSM42-04B2AZAK	\$980.00	Electric Linear
With Electromagnetic Brake	2	DRSM42-04B2AZMK	\$1,187.00	Slides



#### Driver

$\diamondsuit$ Built-in Controller Type			
Product Name	List Price		

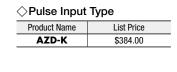






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αstep AZ DRS2

CASTEP AZ

Hollow Rotary Actuators

Connection Cable Sets/Flexible Connection Cable Sets

Use a flexible connection cable set if the cable will be bent.

#### ◇For Motor/Encoder

		$\leq$	
		For Motor	For Encoder
Product Line	Length (m)	Product Name	List Price
	1	CC010VZF2	\$35.00
	2	CC020VZF2	\$50.00
	3	CC030VZF2	\$62.00
Connection	5	CC050VZF2	\$110.00
Cable Sets	7	CC070VZF2	\$136.00
	10	CC100VZF2	\$176.00
	15	CC150VZF2	\$243.00
	20	CC200VZF2	\$310.00
	1	CC010VZR2	\$84.00
	2	CC020VZR2	\$99.00
	3	CC030VZR2	\$111.00
Flexible Connection	5	CC050VZR2	\$141.00
Cable Sets	7	CC070VZR2	\$180.00
	10	CC100VZR2	\$236.00
	15	CC150VZR2	\$332.00
	20	CC200VZR2	\$426.00

		For Motor For Encoder	For Electromagnetic Brake	
Product Line	Length (m)	Product Name	List Price	
Connection Cable Sets	1	CC010VZFB2	\$52.00	
	2	CC020VZFB2	\$67.00	
	3	CC030VZFB2	\$82.00	
	5	CC050VZFB2	\$135.00	
	7	CC070VZFB2	\$166.00	
	10	CC100VZFB2	\$213.00	
	15	CC150VZFB2	\$293.00	
	20	CC200VZFB2	\$372.00	
	1	CC010VZRB2	\$114.00	
	2	CC020VZRB2	\$134.00	
	3	CC030VZRB2	\$151.00	
Flexible Connection	5	CC050VZRB2	\$191.00	
Cable Sets	7	CC070VZRB2	\$240.00	
	10	CC100VZRB2	\$311.00	
	15	CC150VZRB2	\$432.00	
	20	CC200VZRB2	\$551.00	

## Included

#### Actuator

Driver
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Included	Operating Manual	Included Type	Connector	Operating Manual	Type	Operating Manual
Common to All Types	1 Copy	Common to All Tunoo	Connector for CN4 (1 piece)	1 Conv	Connection Cable Sets	-
Common to All Types		Connector for CN1 (1 piece)	1 Copy	Flexible Connection Cable Sets	1 Copy	



Connection Cable Sets/Flexible Connection Cable Sets

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